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## Operating and available power gain circles

### Operating power gain

$$G_P = \frac{P_L}{P_{IN}} = \frac{\text{power delivered to load}}{\text{power input to network}} \quad (1)$$

and it is independent of source impedance.

Design procedure is simple for both unconditionally stable and potentially unstable transistors.

Unconditionally stable bilateral case:

$$G_P = \frac{1}{1 - |\Gamma_{IN}|} |S_{21}|^2 \frac{1 - |\Gamma_L|^2}{|1 - S_{22}\Gamma_L|^2} \quad (2)$$



$$G_P = |S_{21}|^2 \frac{(1 - |\Gamma_L|^2)}{\left(1 - \left|\frac{S_{11} - \Delta \Gamma_L}{1 - S_{22} \Gamma_L}\right|^2\right) |1 - S_{22} \Gamma_L|^2} = |S_{21}|^2 g_p \quad (3)$$

$$g_p = \frac{1 - |\Gamma_L|^2}{1 - |S_{11}|^2 + |\Gamma_L|^2 (|S_{22}|^2 - |\Delta|^2) - 2\text{Re}(\Gamma_L C_2)} \quad (4)$$

$$C_2 = S_{22} - \Delta S_{11}^* \quad (5)$$

$G_P, g_p$  functions only of  $[S], \Gamma_L$ . Procedure for obtaining const. gain circles as before. Final result:

- Circle radius:

$$R_p = \frac{[1 - 2K|S_{12}S_{21}|g_p + |S_{12}S_{21}|^2g_p^2]^{1/2}}{|1 + g_p(|S_{22}|^2 - |\Delta|^2)|} \quad (6)$$


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- distance from origin:

$$d_p = \frac{g_p |C_2^*|}{|1 + g_p (|S_{22}|^2 - |\Delta|^2)|} \quad (7)$$

- Angle:  $g_p$  is a real number. Looking at expr. for center of the circle (eqs. not given), the direction (angle) of the centers will be determined by  $C_2^*$ .

$$C_p = \frac{g_p C_2^*}{1 + g_p (|S_{22}|^2 - |\Delta|^2)} \quad (8)$$

As our intuition tells us,  $g_p$  will have its max. for  $R_p = 0 \Rightarrow$

$$g_{p,max}^2 |S_{12} S_{21}|^2 - 2K |S_{12} S_{21}| g_{p,max} + 1 = 0 \quad (9)$$

$$g_{p,max} = \frac{1}{|S_{12} S_{21}|} (K - \sqrt{K^2 - 1}) \quad (10)$$


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$$\Rightarrow G_{P,max} = \frac{|S'_{21}|}{|S'_{12}|} (K - \sqrt{K^2 - 1}) \quad (11)$$

Given  $G_P$  we select  $\Gamma_L$  from constant operating power gain circles. In order to get max.  $G_P$ ,  $\Gamma_L$  is selected at distance where  $g_{p,max} = G_{P,max} / |S_{21}|^2$ , i.e. calculate  $G_{P,max}$  from eq. 11, find  $g_{p,max} = G_{P,max} / |S_{21}|^2$ , and plug it into eq. for  $d_p$  (eq. 7). Intersection of that with direction of  $C_2^*$  gives  $\Gamma_L$  for  $G_{P,max}$ .

Max. output power obtained if input is conj. matched, i.e.  $\Gamma_s = \Gamma_{IN}^*$ ; in this case the input power is equal to max. available power from source  $\Rightarrow G_{T,max} = G_{P,max}$ . Note that values of  $\Gamma_s$ ,  $\Gamma_L$  that give  $G_{P,max}$  are identical to  $\Gamma_{Ms}$ ,  $\Gamma_{ML}$ .

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## Procedure

- Specify  $G_P$ ; radius, center and angle are given in eqs. above.
- Select the desired  $\Gamma_L$
- For given  $\Gamma_L$  max. output power is obtained by conjugate matching on input, i.e. with

$$\Gamma_s = \Gamma_{IN}^* = S_{11} + \frac{S_{12}S_{21}\Gamma_L}{1 - S_{22}\Gamma_L} \quad (12)$$

This value of  $\Gamma_s$  produces the transducer gain  $G_T = G_P$  (if  $G_P = G_{P,max}$  is specified at the beginning,  $G_T$  will be equal to  $G_{P,max}$ .)



Example 3.8.1. Design for  $G_p = 9\text{dB}$ .

- $|S_{21}|^2 = 4.235$  or  $6.27\text{ dB}$ .  $g_p = G_p/|S_{21}|^2 = 1.875$ .  $K, \Delta, C_2$  calculated before (ex. 3.7.1)
- calculate  $R_p = 0.431$  and  $C_p = 0.508\angle 103.9^\circ$ .
- select some  $\Gamma_L$  point, say pt. A where  $\Gamma_L = 0.36\angle 47.5^\circ$  (note the resistance!)
- calculate  $\Gamma_s$  from known  $\Gamma_L \Rightarrow \Gamma_s = 0.629\angle 175^\circ$

Same procedure can be used to find  $G_{p,max}$  (for simultaneous conjugate matching)  $\Rightarrow$  different circle (actually point):  $g_{p,max} = 3.24$ ,  $R_{p,max} = 0$ ,  $C_{p,max} = 0.718\angle 103.9^\circ$ .

This leads to values for  $\Gamma_{L,max} = 0.718\angle 103.9^\circ$ . Use it to find  $\Gamma_{s,max} = 0.762\angle 177^\circ \Rightarrow$  same as  $\Gamma_{Ms}$ ,  $\Gamma_{ML}$  from before.

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Constant available power gain circles

$$G_A = \frac{P_{AVN}}{P_{AVS}} = \frac{P \text{ avail. from network}}{P \text{ avail. from source}} \quad (13)$$

$$G_A = \frac{1 - |\Gamma_s|^2}{|1 - S_{11}\Gamma_s|^2} |S_{21}|^2 \frac{1}{1 - |\Gamma_{OUT}|^2} \quad (14)$$

Derivation analogous to operating power gain case: exchange 1  $\rightarrow$  2, 2  $\rightarrow$  1,  $L \rightarrow S$ .

$$g_a = \frac{G_A}{|S_{21}|^2} \quad C_1 = S_{11} - \Delta S_{22}^* \quad (15)$$



$$R_a = \frac{[1 - 2K|S_{12}S_{21}|g_a + |S_{12}S_{21}|^2g_a^2]^{1/2}}{|1 + g_a(|S_{11}|^2 - |\Delta|^2)|} \quad (16)$$

$$C_a = \frac{g_a C_1^*}{1 + g_p(|S_{22}|^2 - |\Delta|^2)} \quad (17)$$

By plotting const. available gain circles a  $\Gamma_s$  can be picked up to produce desired  $G_A$ . With  $\Gamma_s$  known, max. power on output is obtained for conjugate matched load so that

$$\Gamma_L = \Gamma_{OUT}^* = \left( S_{22} + \frac{S_{12}S_{21}\Gamma_s}{1 - S_{11}\Gamma_s} \right)^* \quad (18)$$

For  $\Gamma_L = \Gamma_{OUT}^* \Rightarrow G_T = G_A$ .

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## Potentially unstable bilateral case

We have to worry about stability! Procedure is still the same:

- specify  $G_p$  and draw const. operating gain circles. (calc.  $R_p, C_p$ )
- draw output stability circle (calc.  $r_L, C_L$ ; remember that they give  $\Gamma_L$ -s for which  $|\Gamma_{IN}| = 1$ )
- choose  $\Gamma_L$  in stable region (stay away from circle)
- draw input stability circles (calc.  $r_s, C_s$ ).
- calculate  $\Gamma_{IN}$  and see if  $\Gamma_s = \Gamma_{IN}^*$  is in the stable region
- if  $\Gamma_s$  is not in stable region, or is too close to stability circle:
  - a) select  $\Gamma_s$  arbitrarily, b) select new  $G_p$ , c) try different  $\Gamma_L$



$\Gamma_s, \Gamma_L$  should be away from the stability circles to avoid oscillations during tuning or due to variations of parameters.

Example 3.8.2. Design for 10 dB.

- stability:  $K = 0.4 < 1 \Rightarrow$  potentially unstable.  $G_{MSG} = 31 = 14.9$  dB.
- calc. const. gain circles:  $R_p = 0.473, C_p = 0.57 \angle 97^\circ$
- output stability circle:  $r_L = 0.34, C_L = 1.18 \angle 97^\circ$ ; note that  $C_L$  and  $C_p$  are on the same line; obvious from their eqs.
- stability region: since  $|S_{11}| < 1$ , stable region includes origin.



- select  $\Gamma_L$  somewhere on const. gain circle. (different choices possible: max. resistance, min. SWR etc). pt A has  $\Gamma_L = 01.497^\circ$
- on input:  $\Gamma_s = \Gamma_{OUT}^* = 0.52 \angle 179^\circ$ ; is it stable?
- input stability circle:  $r_s = 1, C_s = 1.67 \angle 171^\circ$ . Since  $|S_{22}| < 1$ , origin is in stable region  $\Rightarrow \Gamma_s$  is stable point. (construct these on S-chart).



Yet another method for amplifier design

M.L. Edwards et al., “A Deterministic Approach for Designing Conditionally Stable Amplifiers,” *IEEE MTT*, vol. 43, no. 7, pp. 1567–1575, 1995.

Basic problem: input and output treated separately even though each affects the other. Fig. 1 for basic procedure for the methods discussed so far:

1. Pick a “suitable” source reflection coefficient  $\Gamma_s$
2. design input matching network
3. calculate  $\Gamma_{OUT}$  and take  $\Gamma_L = \Gamma_{OUT}^*$
4. is  $\Gamma_L$  in stable region?



What to do if  $\Gamma_L$  is not stable?

1. accept the give  $\Gamma_L$  and design the OMN
2. change  $\Gamma_L$  to be stable but “close” to  $\Gamma_{OUT}^*$
3. change  $\Gamma_s$  and hope that new  $\Gamma_L$  will be stable

Problems: possibly unstable (1) and iterative (2,3).

Distinction: stability on input and output separated.  $\Rightarrow$  circuit can be output stable ( $|\Gamma_{OUT}| < 1$ ) but input unstable ( $|\Gamma_{IN}| > 1$ ) and vice-versa.

Definition: **Jointly stable** I/O circuits are those that have  $|\Gamma_{OUT}(\Gamma_s)| < 1$  and  $|\Gamma_{IN}(\Gamma_{OUT}^*(\Gamma_s))| < 1$ .

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Idea: If stable/unstable region of  $\Gamma_L$  plane could be represented in the  $\Gamma_s$  plane, than we could devise a non-iterative scheme for picking  $\Gamma_s$  and  $\Gamma_L$ . (note:  $\Gamma_L$  is really function of  $\Gamma_s$  since we assume  $\Gamma_s = \Gamma_{OUT}^*$ ). Recall:

$$\Gamma_{IN} = f(\Gamma_L) = \frac{S_{11} - \Delta\Gamma_L}{1 - S_{22}\Gamma_L} \quad (19)$$

$$\Gamma_{OUT} = g(\Gamma_s) = \frac{S_{22} - \Delta\Gamma_s}{1 - S_{11}\Gamma_s} \quad (20)$$

Similar eqs. can be obtained for  $\Gamma_L$  (from (19)), and  $\Gamma_s$  (from (20) ).

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Define:

1. *Output stable region in the source plane* where  $|\Gamma_{OUT}(\Gamma_s)| < 1$  (= input stability circle), and
2. *input stable region in the source plane* where  $\Gamma_{IN}(|\Gamma_{OUT}^*(\Gamma_s)|) < 1$  (= output stability circle, but in  $\Gamma_s$  plane).

For (1), see fig. 2 (two cases:  $D_1 > 0$  and  $D_1 < 0$ , where  $D_1$  depends only on S-matrix).

Section III of the paper shows that  $|k| < 1$  if and only if stability circle intersects the unit circle. Why is that important?

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For  $|k| < 1$ , stability circle intersects the unit circle in two points that are **common to all available gain circles** which are called invariant points.  $\Rightarrow$  geometric relationship between the stability circle, the gain circle and the unit circle can be determined solely by comparing the centers of the circles.

The invariant (intersection) points are given by

$$\Gamma_s^\pm = \frac{B_1 \pm \sqrt{4|C_1|^2 - B_1^2}}{2C_1} \quad (21)$$

But, what can we learn about the gain  $g_a$  ( $G_A = g_a |S_{21}|^2$ ) from all this?

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Because of the discussion above, only the position of the center (and they are all on one line) matters. How does  $g_a$  change along this line  $\Gamma_s = x\hat{c}_s$ ? Based on the derivative and some reasoning  $\Rightarrow$  the gain function  $g_a$  is a **monotonic** function of  $x$  whenever  $|k_s| < 1$ . See fig. 3 for illustration. For  $|\Gamma_s| = 1 \Rightarrow g_a = 0$ , and  $g_a \rightarrow \infty$  when  $\Gamma_s$  is on stability circle.

Not very useful, unless we can show input stable region in the source plane.

Through equations (section V) it is shown that the center of this circle is on the same line as available gains and that it intersects the invariant points!  $\Rightarrow$  **input stable boundary in the source plane is an available gain circle.**

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The gain that corresponds to this boundary (IS) is :

$$g_{is} = \frac{2k}{|S_{12}S_{21}|} \Rightarrow G_{IS} = 2k \left| \frac{S_{21}}{S_{12}} \right| = 2k \text{ MSG} \quad (22)$$

Question: when/if is this  $g_{is}$  upper bound for the available gain?

There is a max. of available gain when source impedance  $\Gamma_s$  is required to be passive and **jointly stable**, called max. jointly stable available gain.

The analysis requires examination of different combination of these circles: see Table 1. Two obvious requirements:  $|\Gamma_s| < 1$  (passive source region) and  $|\Gamma_{OUT}(\Gamma_s)| < 1$  (output stable region). For  $|\Gamma_{IN}(\Gamma_{OUT}^*(\Gamma_s))| < 1$  (input stable region) stable region can be either inside or outside the  $g_{IS}$  circle.

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Different cases in Figs. 4 – 8. Case I in some detail.

Conclusion: when  $0 < k < 1$  then the jointly stable region overlaps with the USC, i.e.  $\Gamma_s$  from the overlapping region result in an output whose conjugate match is located on the stable side of the load stability circle. Also, the gain is limited to  $G_{IS}$ .

For  $-1 < k < 0$  no passive source impedance will result in joint stability.

For  $0 < k < 1 \Rightarrow$  the maximum available gain for jointly stable source impedances is  $G_{IS} = 2kMSG (= G_{MSM})$ .

Similar reasoning can be extended to operating power gain (source exchanged with load).

Example of design for 6 GHz amplifier with conditionally stable transistor.

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