
1.1 Mathematical description

Uniform transm. lines: dimensions and el. properties are identical at all planes transverse to the direction of propagation.

Length of the transm. line need not be negligible compared to the wavelength. Extension of a.c. circuit theory to DISTRIBUTED circuits.

Define resistance, conductance, inductance and capacitance per unit length: R' , G' , L' , C' for uniform transm. line.

Explain difference between R' and G'



- R' related to dimensions and conductivity of (metallic) conductors
- G' related to loss tangent of the insulating material between
- L' related to magnetic flux linking the conductors
- C' related to charge on conductors

Fig. 3-1 (analogy to twin lead or coax)

Δz represents a “small” section of the transm. line — small is relative to the wavelength



Kirchoff's laws for V and I for a small segment (sketch)

$$V = (R' \Delta z) I + (L' \Delta z) \frac{\partial I}{\partial t} + (V + \Delta V) \quad (1)$$

$$I = (I + \Delta I) + (V + \Delta V)(G' \Delta z) + (C' \Delta z) \frac{\partial (V + \Delta V)}{\partial t} \quad (2)$$

division by Δz gives:

$$\frac{V - (V + \Delta V)}{\Delta z} = R' I + L' \frac{\partial I}{\partial t} \quad (3)$$

$$\frac{I - (I + \Delta I)}{\Delta z} = (V + \Delta V)G' + C' \frac{\partial (V + \Delta V)}{\partial t} \quad (4)$$



Taking the limit $\Delta z \rightarrow 0$ gives:

$$-\frac{\partial V}{\partial z} = R'I + L'\frac{\partial I}{\partial t} \quad \text{and} \quad -\frac{\partial I}{\partial z} = VG' + C'\frac{\partial V}{\partial t} \quad (5)$$

Analogous to the eqs. we had for E and H. Combining produces:

$$\frac{\partial^2 V}{\partial z^2} = L'C'\frac{\partial^2 V}{\partial t^2} + (R'C' + G'L')\frac{\partial V}{\partial t} + R'G'V \quad (6)$$

and similar for I.

For perfect conductor $R' = 0$, perfect insulator $G' = 0$



$$\frac{\partial^2 V}{\partial z^2} = L' C' \frac{\partial^2 V}{\partial t^2} \quad \text{and} \quad \frac{\partial^2 I}{\partial z^2} = L' C' \frac{\partial^2 I}{\partial t^2} \quad (7)$$

These are wave eqs and their solutions are “EM wave”-like , traveling along both directions. Both current and voltage waves.

In general solutions will satisfy $f(t \pm \sqrt{L' C'} z)$.

Look at $f(z = 0) = f(t) = V$ and at another $z = z_1$ where $V = f(t - \sqrt{L' C'} z_1)$. By the time $t = \sqrt{L' C'} z_1$ the value inside () is the same as for $z = 0 \Rightarrow$ only difference is time delay of $\sqrt{L' C'} z_1$.



The velocity of propagation of such wave is

$$v = \frac{z_1}{t_d} = \frac{z_1}{z_1 \sqrt{L'C'}} = \frac{1}{\sqrt{L'C'}} \quad (8)$$

Note that $f(t + \sqrt{L'C'}z)$ travels in negative direction.

I and V travel with the same velocity.

for EM waves we found that E/H was constant: same here, but instead of η we have

$$\text{CHARACTERISTIC IMPEDANCE } Z_0 = \frac{V}{I} = \sqrt{\frac{L'}{C'}} \quad (9)$$



1.2 Transient behavior

Charging of an infinite transmission line. (fig. 3-2)

Idea of sequential current increases, capacitance charging, current increase etc. Instantaneous changes impossible due to L and C.

V and I generate each other and travel with the same velocity v .

Line infinite \Rightarrow only + directed wave. Since V/I is constant, only $Z_0 (= 100\Omega)$ is seen at all times. \Rightarrow infinite line presents Z_0 load to the battery and it keeps drawing current.

Note that the steady state at the input is reached immediately.



Finite length: open circuit. Fig. 3-3.

At $t = 0$, $V = 10V$ appears at input of transm. line, i.e. line behaves like and infinite line \Rightarrow input impedance $= Z_0$ at $t = 0$. Input current $I_{in} = VG/(R_G + Z_0) = 20/200 = 0.1A$ and input voltage $V_{in} = 10V$. These stay constant until later (when reflected wave arrives).

For propagation velocity $v = 2 \cdot 10^8 m/s$, time it takes the wave to get to the end is $t = l/v = 4/2 \cdot 10^8 = 20ns$.

Fig. 3-3 a) shows the situation at half the time it takes to travel to the end, and 3-3 b) is for time just before reaching the end.



Something must happen at the end of the line:

- constant ratio $V^+/I^+ = Z_0$ must be preserved for the traveling wave
- $Z = \infty$ since the end is open-circuited.

Reflection of traveling waves at O-C makes it possible to satisfy both requirements.

For voltage and current at the load we have $V_L = V^+ + V^-$ and $I_L = I^+ - I^-$. Since $I_L = 0 \Rightarrow I^+ = I^-$ and $V^- = I^- Z_0 = I^+ Z_0 = V^+$. Finally, $V_L = 2V^+ = 20V$.

Define reflection coefficient $\Gamma = V^-/V^+ = I^-/I^+$ and is =1 for O-C case.



Current becomes zero as I^- wave returns and V goes to 20V.

At the generator end $V^-/I^- = Z_0 = 100\Omega$ is the same as the impedance of the generator, so no need for additional requirements to be satisfied \Rightarrow no more reflections.

Resistive termination

Fig. 3-4. part a) is as before. At the end of the line $Z_0 \neq R_L$ and Ohm's law is not satisfied if we also want to keep the Z_0 constant. Solution: reflections must occur at load end.

$$\begin{aligned} V_L &= V^+ + V^-, \quad I_L = I^+ - I^- = (V^+ - V^-)/Z_0. \quad \text{Ohm's law} \\ V_L &= I_L R_L \Rightarrow \end{aligned}$$



$$R_L = \frac{V^+ + V^-}{V^+ - V^-} Z_0 = \frac{1 + \Gamma_L}{1 - \Gamma_L} Z_0 \text{ or } \Gamma_L = \frac{R_L - Z_0}{R_L + Z_0} \quad (10)$$

In steady-state transm. line is a short circuit.

Analogy with Γ for TEM waves ($= (\eta - \eta_0) / (\eta + \eta_0)$).

For resistance Γ is real but it is complex for other terminations.

$\Gamma = 1$ for O-C, and $\Gamma = -1$ for S-C (short circuit).

For $R_L = Z_0$ no reflections occur since Ohms law is automatically satisfied.



Multiple reflections

Both R_L and $R_G \neq Z_0$! see Fig. 3-5.

At $t=0$ generator sees Z_0 (as before) $\Rightarrow I^+ = 90/300 = 0.3A$ and $V^+ = 30V$. R_L has no influence.

After 20ns there is a reflection on load end: $\Gamma_L = (25 - 100)/125 = -0.6$ resulting in $V^- = V^+\Gamma = -18V$.

Total voltage $V_{total} = V^+ + V^- = 12V$. Similarly for reflected and total currents we have $I^- = \Gamma I^+ = -0.18A$ and $I_{tot} = I_L = 0.3 + 0.18 = 0.48A$

These two combined waves reach source end, and there is another reflection ($R_G \neq Z_0$): $\Gamma_G = (R_G - Z_0)/(R_G + Z_0) = V_{refl}/V_{inc} = I_{refl}/I_{inc} = 1/3$.



To find the reflected part $V_{ref} = \Gamma_G V^- = -6V$; etc.

Now the incident (incoming) wave is $V^- = -18V$ which gives $V_{ref} = -6V$ and new total voltage $V_{tot} = 12 - 6 = 6V$

Another reflection at the load end, this time the incident wave is $-6V$ so that $V_{ref} = -6 * (-0.6) = 3.6V$ for the new $V_{tot} = 6 + 3.6 = 9.6V$.

Amplitudes of reflected waves get smaller with each reflection (why?).

Final d.c. value $V = 90 * R_L / (R_G + R_L) = 10V$. Fig. 3-6 shows the time evolution of the input voltage.



Bewley's diagram: voltage and current as functions of time and position. Fig. 3-7. Construct constant z diagram or find value of V or I for fixed t .

For fixed z ($=2m$) intersections represent arrivals of wave fronts; voltages summed up; forward current waves added but reflected ones subtracted.

Fixed t : sum of voltages at any z above the line gives V variation with z (same for I)

Ringing occurs: period $T=80\text{ns}$ ($2 \times$ round trip) or $f = 1/T = 12.5\text{MHz}$. For $v = 2 \cdot 10^8 \Rightarrow \lambda f = v$ and $\lambda = 16m$ or $l = \lambda/4$.

Interesting result: d.c. source produces high frequency oscillations. If both Γ -s were unity \Rightarrow continuous oscillations, i.e. resonant circuit.



1.3 Sinusoidal excitation

Equations become (using phasor notation):

$$-\frac{d\hat{V}}{dz} = (R' + j\omega L')\hat{I} = Z'\hat{I} \quad (11)$$

$$-\frac{d\hat{I}}{dz} = (G' + j\omega C')\hat{V} = Y'\hat{V} \quad (12)$$

As for EM waves these are combined:

$$\frac{d^2\hat{V}}{dz^2} = Z'Y'\hat{V} \Rightarrow \hat{V} = \hat{V}_0^+ e^{-\gamma z} + \hat{V}_0^- e^{\gamma z} = V^+ + V^- \quad (13)$$

As before, γ is (complex) propagation constant.

$$\gamma = \sqrt{Z'Y'} = \sqrt{(R' + j\omega L')(G' + j\omega C')} = \alpha + j\beta \quad (14)$$



For current we have:

$$\hat{I} = \hat{I}_0^+ e^{-\gamma z} - \hat{I}_0^- e^{+\gamma z} = \hat{I}^+ - \hat{I}^- \quad (15)$$

Characteristic impedance (voltage to current ratio fro traveling waves)

$$Z_0 = \frac{V_0^+}{I_0^+} = \frac{V_0^-}{I_0^-} = \sqrt{\frac{Z'}{Y'}} = \sqrt{\frac{R' + j\omega L'}{G' + j\omega C'}} \quad (16)$$

Voltages and currents are phasor quantities and depend on conditions on load and generator end.

Power flow : $P = \text{Re}(\hat{V}\hat{I}^*) = IV \cos \Theta_{pf}$

Example 3-1.



Low-loss lines

At high frequency: $R' \ll \omega L'$ and $G' \ll \omega C'$. Almost always true in MW range.

$$Z_0 = \sqrt{\frac{L'}{C'}} \Omega, \quad \alpha \approx \frac{R'}{2Z_0} + \frac{G'Z_0}{2} \text{ Np/length} \quad (17)$$

$$\beta \approx \omega \sqrt{L'C'} \quad v = \frac{1}{\sqrt{L'C'}} \quad \lambda = \frac{\lambda_0}{c\sqrt{L'C'}} \quad (18)$$

Conclusions:

- Eqs. for Z_0, v, β, λ \approx the same as for lossless lines.



- Since Z_0 is practically real, the average power flow in a traveling wave at any point z is product of rms voltage and current $P^+ = V^+I^+$ and $P^- = V^-I^-$.
- For single frequency signals \Rightarrow finite R' , G' introduce attenuation on propagating waves ($e^{-\alpha\Delta z}$ for power it's square).

Similar to EM waves in lossy dielectric. Reason: there is a wave associated with sinusoidal waves but now it is guided.



Coaxial transmission lines

Fig. 3-8 shows E and H field distribution.

$$E = \frac{V}{r \ln \frac{b}{a}} \quad H = \frac{I}{2\pi r} \quad (19)$$

Average power flow:

$$P = \int_S \vec{\mathcal{E}} \times \vec{\mathcal{H}} \cdot d\vec{s} \quad (20)$$

In cylindrical coordinates: $d\vec{s} = r d\phi dr$ ($d\vec{s}$ is element normal to the plane of paper, i.e. cross-sectional area; sketch)

$$P = \int_a^b \int_0^{2\pi} \frac{VI}{2\pi r^2} \left(\ln \frac{b}{a} \right)^{-1} r d\phi dr = VI \quad (21)$$

(why these limits?)



Interpretation: power flow associated with the voltage and current waves is just another way of viewing EM propagation in the region between conductors!

From early on: $C = 2\pi\epsilon_0\epsilon_r l / \ln(b/a)$. Divide by l to get C' .

Similarly $L = \mu_0\mu_r l \ln(b/a) / (2\pi)$.

$$v = \frac{1}{\sqrt{L'C'}} = \frac{1}{\sqrt{\mu_0\mu_r\epsilon_0\epsilon_r}} = \frac{c}{\sqrt{\mu_r\epsilon_r}} \quad (\text{familiar?}) \quad (22)$$

$$Z_0 = \sqrt{\frac{L'}{C'}} = \sqrt{\frac{\mu_0\mu_r}{4\pi^2\epsilon_r\epsilon_0}} \ln \frac{b}{a} = 60 \sqrt{\frac{\mu_r}{\epsilon_r}} \ln \frac{b}{a} \quad (23)$$



1.4 Terminated transm. lines

Discussion of various loads on transm. lines.

Alternative view: tr. line terminated in its Z_0 has no reflections — based on infinite line picture. Conclusion: line terminated in its Z_0 is equivalent to infinitely long line and has no reflections. Input impedance = Z_0 .

Fig. 3–9, $\hat{V}_{in}, \hat{I}_{in}$ at point $z=0$:

$$\hat{V}_{in} = \frac{Z_0}{Z_G + Z_0} \hat{V}_G \quad \hat{I} = \frac{\hat{V}_G}{Z_G + Z_0} \quad (24)$$

No reflections present $\Rightarrow \hat{V}_{in} = \hat{V}_0^+, \hat{I}_{in} = \hat{I}_0^+$.



\hat{V} , \hat{I} still vary along the line:

$$\hat{V} = \hat{V}_0^+ e^{-\gamma z} \quad \hat{I} = \hat{I}_0^+ e^{-\gamma z} \quad (25)$$

At the load end this gives ($z=l$):

$$\hat{V}_L = \frac{Z_0}{Z_G + Z_0} \hat{V}_G e^{-\alpha l} \quad L - \beta l \quad \hat{I}_L = \frac{\hat{V}_G}{Z_G + Z_0} e^{-\alpha l} \quad L - \beta l \quad (26)$$

What's the power absorbed by load? $P_L = V_L I_L$ (rms values) since Z_0 is real.

$$P_L = Z_0 \left| \frac{V_G}{Z_G + Z_0} \right|^2 e^{-2\alpha l} \quad (27)$$

magnitude needed since Z_G may be complex



General case (with reflections)

If $Z_L \neq Z_0 \Rightarrow$ reflections. Starting point is

$$\hat{V} = \hat{V}_0^+ e^{-\gamma z} + \hat{V}_0^- e^{+\gamma z} = \hat{V}^+ + \hat{V}^- \quad \hat{I} = \hat{I}_0^+ e^{-\gamma z} - \hat{I}_0^- e^{+\gamma z} \quad (28)$$

Reflection coeff. Γ was defined only at the load or generator end
— no need for such a restriction \Rightarrow define it anywhere on line:

$$\Gamma(z) = \frac{\text{refl. V or I}}{\text{incident V or I}} = \frac{\hat{V}^-}{\hat{V}^+} = \frac{\hat{I}^-}{\hat{I}^+} \quad (29)$$

At load end we have:

$$\Gamma_L = \frac{\hat{V}_0^- e^{\gamma l}}{\hat{V}_0^+ e^{-\gamma l}} = \frac{\hat{V}_0^-}{\hat{V}_0^+} e^{2\gamma l} \quad (30)$$



For convenience: transform coordinated so that zero is at load end and + direction is towards generator (Fig. 3-10). New coordinate: $d=|l-z$.

Voltage wave somewhere on the tr. line:

$$\hat{V} = V_0^+ e^{-\gamma l} \left[\underbrace{e^{\gamma d}}_{\text{gen.} \rightarrow \text{load}} + \underbrace{\Gamma_L e^{-\gamma d}}_{\text{load} \rightarrow \text{gen.}} \right] \quad (31)$$

$$\hat{I} = \hat{I}_0^+ e^{-\gamma l} \left[e^{\gamma l} - \Gamma_L e^{-\gamma d} \right] \quad (32)$$



Γ at any point is:

$$\Gamma = \Gamma_L e^{-2\gamma d} = \Gamma_L e^{-2\alpha d} \angle -2\beta d = |\Gamma_L| e^{-2\alpha d} \angle (\phi_L - 2\beta d) \quad (33)$$

Interpretation: Input wave attenuated by $e^{-\alpha d}$ on the way to load; phase shifted by $-\beta l$. After reflection attenuated by another $e^{\alpha d} \Rightarrow \text{total} = e^{-2\alpha d}$. Only a fraction reflected, as determined by Γ_L .

On input terminals the mag. of refl. wave is $|\Gamma_L| e^{-2\alpha l}$. Phase shift = $-2\beta l$, but Γ_L adds its own $\Rightarrow \text{total} = \phi_L - 2\beta l$.

For $\alpha = 0$, $|\Gamma|$ is independent of d , but phase angle is still function of d .



$$d = 0 \Rightarrow \hat{V}_L = \hat{V}_0^+ e^{-\gamma l} [1 + \Gamma_L] \quad \hat{I}_L = \hat{I}_0^+ e^{-\gamma l} [1 - \Gamma_L] \quad (34)$$

$$\Rightarrow Z_L = \frac{\hat{V}_L}{\hat{I}_L} = Z_0 \frac{1 + \Gamma_L}{1 - \Gamma_L} \quad \text{or} \quad \frac{Z_L}{Z_0} = \bar{Z}_L = \frac{1 + \Gamma_L}{1 - \Gamma_L} \quad (35)$$

$$\Gamma_L = \frac{Z_L - Z_0}{Z_L + Z_0} = \frac{\bar{Z}_L - 1}{\bar{Z}_L + 1} \quad \text{also} \quad \Gamma_L = \frac{1 - \bar{Y}_L}{1 + \bar{Y}_L} \quad (36)$$

where $Y_L = 1/Z_L$

Analogous to equations in transient case. Difference is in steady state a.c. analysis \Rightarrow valid for any complex load. Also, merger of a.c. circuit theory (impedance) and wave theory (refl. coefficient).



Extend the concept to any point on the tr. line:

$$Z = \frac{\hat{V}}{\hat{I}} = Z_0 \frac{1 + \Gamma(d)}{1 - \Gamma(d)} \quad \text{and} \quad Y = Y_0 \frac{1 - \Gamma(d)}{1 + \Gamma(d)} \quad (37)$$

Represents total Z or Y to the right of point d.

Reflection means standing waves. When $Z_L \neq Z_0 \Rightarrow \Gamma_L \neq 0$ and standing waves exist.

Take the short circuit (S-C) load: same as wave reflection of perfect conductor. see fig. 2-24, 2-25. Successive minima are $\lambda/2$ apart, 1 shifted by $\lambda/4$ relative to V.



General case: \hat{V} is sum of phasor quantities $\hat{V}^+ + \hat{V}^-$.

Lossless case: two counter-rotating vectors of fixed magnitude (fig. 2-28). When in phase \rightarrow maximum

$$V_{max} = V^+ + |\Gamma|V^+ = (1 + |\Gamma|)V^+ \quad (38)$$

$\lambda/4$ away there is a minimum (phasors 180° out of phase)

$$V_{min} = V^+ - |\Gamma|V^+ = (1 - |\Gamma|)V^+ \quad (39)$$

Standing wave ratio

$$\text{SWR} = \frac{V_{max}}{V_{min}} = \frac{1 + |\Gamma|}{1 - |\Gamma|} \quad \text{and} \quad |\Gamma| = \frac{\text{SWR} - 1}{\text{SWR} + 1} \quad (40)$$



For lossless line $SWR = \text{const.}$, but not otherwise (not useful).

example 3.2

Special Cases

A) Short circuit: $Z_L = 0 \Rightarrow \Gamma_L = -1$, $SWR = \infty$. At $d=0$ ($z=l$) $V=0$; other nulls occur at multiple of $\lambda/2$.

I is maximum at the load ($d=0$), its rms value is $2I_0^+$.

Since V and I are displaced by $\lambda/4$, at $d = \lambda/4$, we have $Z \rightarrow \infty$, i.e. short circuit is transformed into open circuit !!!

B) Open circuit: $Y_L = 0$, $\Gamma_L = 1$, $SWR = \infty$. See fig. 3-11 for standing waves. At $d=0$, $I=0$; $V_{max} = 2V_0^+$ and at $d = \lambda/4$ we have $Z = 0$, i.e. O-C becomes S-C !!!



C) Reactive loads:

$$Z_L = jX \Rightarrow \Gamma_L = \frac{j\bar{X} - 1}{j\bar{X} + 1} = 1 \angle \pi - 2 \arctan \bar{X} \quad (41)$$

For $\underbrace{\bar{X} = +1}_{??} \Rightarrow \Gamma_L = 1 \angle 90^\circ$; for $\underbrace{\bar{X} = -1}_{??} \Rightarrow \Gamma_L = 1 \angle -90^\circ$. In either case $|\Gamma| = 1, SWR \rightarrow \infty$.

Interpret: reactance cannot absorb power \Rightarrow all power in incident wave must be reflected (analogous to S-C and O-C in this respect). Consequence: $|\Gamma_L| < 1$ only if Z_L has a resistive component.

Fig. 3-12 for SW pattern ($Z_L = jZ_0$); first voltage null is $3\lambda/8$ away from $d=0$



D) Resistive loads:

$$\Gamma_L = \frac{R_L - Z_0}{R_L + Z_0} \Rightarrow \text{real} \quad (42)$$

For $R_L = Z_0 \Rightarrow$ no reflections.

For $R_L > Z_0 \Rightarrow \Gamma_L > 0$, V_{max} and I_{min} are at the load. (why?)
 $\text{SWR} = R_L/Z_0$.

For $R_L < Z_0 \Rightarrow \Gamma_L < 0$, and V_{min} , I_{min} at the load. $\text{SWR} = Z_0/R_L$

$\text{SWR} = R_L/Z_0$ or Z_0/R_L whichever is > 1 .

$|\Gamma_L| < 1$, i.e. some power is absorbed.



1.5 Power flow

Generally $P = \text{Re}(\hat{V}\hat{I}^*) = VI \cos \Theta_{pf}$

Direction of flow from generator to load $\hat{V} = \hat{V}_0^+ e^{-\gamma z} + \hat{V}_0^- e^{\gamma z} = \hat{V}^+(1 + \Gamma)$ and $\hat{I} = \hat{I}^+ - \hat{I}^- = I^+(1 - \Gamma)$

The power becomes

$$\begin{aligned} P &= \text{Re} \left[(1 + \Gamma)(1 - \Gamma)^* \hat{V}^+ \hat{I}^{+*} \right] \\ &= \text{Re} \left[(1 + \Gamma)(1 - \Gamma^*) \frac{\hat{V}^+ V^{+*}}{Z_0^*} \right] \\ &= \text{Re} \left[(1 + \Gamma - \Gamma^* - |\Gamma|^2) \frac{|V^+|^2}{Z_0^*} \right] \end{aligned} \quad (43)$$

Low-loss, high freq. $\Rightarrow Z_0$ is real $\Rightarrow \Gamma - \Gamma^*$ is imaginary.



$$P = (1 - |\Gamma|^2) \frac{|V^+|^2}{Z_0} = (1 - |\Gamma|^2) P^+ = P^+ - |\Gamma|^2 P^+ = P^+ - P^-$$

For Z_0 real net power flow at any point on the line is the difference between the power in the **forward wave** P^+ and in the **reflected wave** P^- . Note: Γ is function of position.

How about input terminals:

$$P_{in} = P_{in}^+ (1 - |\Gamma_{in}|^2) \quad P_L = P_L^+ (1 - |\Gamma_L|^2) \quad (44)$$

Remember that + and - signs indicate **traveling waves**.

$$P_{in}^+ = \underbrace{(V_0^+)^2}_{\text{magn.}} / Z_0, \quad P_L^+ = V_L^{+2} / Z_0 = P_{in}^+ e^{-2\alpha l} \quad (45)$$



i.e. incident power at the load is input power attenuated along the line of length l . For lossless lines $\Rightarrow P_{in}^+ = P_L^+ = P^+$

NET power flow is position dependent and we need to determine P^+ at any point.

For real Z_0 , \hat{V}^+ , \hat{I}^+ are in phase $\Rightarrow P^+ = \frac{V^{+2}}{Z_0} = \frac{V_0^{+2} e^{-2\alpha z}}{Z_0}$

\hat{V}_0^+ and its rms value V_0^+ are obtained from Kirchoff's laws at input:

$$\hat{V}_G = \hat{V}_{in} + \hat{I}_{in} Z_G = (\hat{V}_0^+ + \Gamma_{in} \hat{V}_0^+) + Z_G \frac{\hat{V}_0^+ - \Gamma_{in} \hat{V}_0^+}{Z_0} \quad (46)$$



$$\hat{V}_0^+ = \frac{\hat{V}_G Z_0}{(Z_G + Z_0)(1 - \Gamma_G \Gamma_L e^{-2\gamma l})} \quad (47)$$

where $\Gamma_L = (Z_G - Z_0)/(Z_G + Z_0)$

Given \hat{V}_G , Z_G , Z_L (circuit) and Z_0 , γ , l (line) we can find V_0^+ .

Alternative form:

$$\hat{V}_0^+ = \frac{\hat{V}_G(1 - \Gamma_G)}{2(1 - \Gamma_G \Gamma_{in})} = \frac{\hat{V}_G(1 - \Gamma_G)}{2(1 - \Gamma_G \Gamma_L e^{-2\gamma l})} \quad (48)$$

With V_0^+ known P can be determined.



Two different approaches: a) multiple reflection, b) steady state a.c. circuit. What's the relationship?

case 1) Either $\Gamma_L = 0$ or $\Gamma_G = 0$ so no multiple reflections occur. Initial forward traveling wave from voltage divider $Z_G + Z_0$,
 $\Rightarrow \hat{V}_0^+ = \hat{V}_G Z_0 / (Z_G + Z_0)$. Same as in eq. (47).

case 2) Multiple reflections. \hat{V}_0^+ represents phasor sum of all the forward traveling waves at input ($z=0$).

Initial wave: $\hat{V}_0^+(1) = \hat{V}_G Z_0 / (Z_G + Z_0)$

2nd one: $\hat{V}_0^+(2) = \Gamma_G \Gamma_L e^{-2\gamma l} \hat{V}_G Z_0 / (Z_G + Z_0)$

3rd one: $\hat{V}_0^+(3) = (\Gamma_G \Gamma_L e^{-2\gamma l})^2 \hat{V}_G Z_0 / (Z_G + Z_0)$

etc.



Final result is the sum of all of the above; limit of the series is (when $|\Gamma_L \Gamma_G e^{-2\gamma l}| < 1$) is $(1 - \Gamma_L \Gamma_G e^{-2\gamma l})^{-1}$. This leads to the same expression as in a.c. theory (eq. (47)).

Back to power calculation: $P^+ = V_0^{+2} e^{-2\alpha z} / Z_0$. Now plug in expr. for V_0^+ (eq. 48))

$$P^+ = \frac{V_G^2}{4Z_0} \left| \frac{1 - \Gamma_G}{1 - \Gamma_G \Gamma_{in}} \right|^2 e^{-2\alpha z} \quad (49)$$

so, for $z=0$ we have

$$P_{in}^+ = \frac{V_G^2}{4Z_0} \left| \frac{1 - \Gamma_G}{1 - \Gamma_G \underbrace{\Gamma_{in}}_{=\Gamma_L e^{-2\gamma l}}} \right|^2 \quad (50)$$



Useful concept: available power from source $P_A = V_G^2/(4R_G)$
where $R_G = \text{Re}(Z_G)$

$$P_{in}^+ = P_A \frac{1 - |\Gamma_G|^2}{|1 - \Gamma_G \Gamma_{in}|^2} \quad (51)$$

Finally, what is the NET input power?

$$P_{in} = P_{in}^+ (1 - |\Gamma_{in}|^2) = P_A \frac{(1 - |\Gamma_G|^2)(1 - |\Gamma_{in}|^2)}{|1 - \Gamma_G \Gamma_{in}|} \quad (52)$$

Power deliver to the load:

$$P_L = P_A \frac{(1 - |\Gamma_G|^2)(1 - |\Gamma_L|^2)}{|1 - \Gamma_G \Gamma_L e^{-2\gamma l}|^2} e^{-2\alpha l} \quad (53)$$



or for lossless line:

$$P_{in} = P_L = P_A \frac{(1 - |\Gamma_G|^2)(1 - |\Gamma_L|^2)}{|1 - \Gamma_G \Gamma_L e^{-j2\beta l}|^2} \quad (54)$$

In this case $|\Gamma_{in}| = |\Gamma_L|$ then $\Gamma_{in} = \Gamma_L e^{-j2\beta l}$

Assume that the input is matched $Z_G = Z_0$ then $\Gamma_G = 0$ and P_L independent of frequency and phase angle βl ($\beta = \omega/v$).

Therefore, for matched input $\hat{V}_0^+ = \hat{V}_G/2$ and $P_{in}^+ = P_A = V_G^2/(4Z_0)$ so that

$$P_{in} = P_A(1 - |\Gamma_{in}|^2) \text{ and } P_L = P_A e^{-2\alpha l}(1 - |\Gamma_L|^2) \quad (55)$$



Lossless line, generator end matched; if load is matched as well
 \Rightarrow all of P_A is delivered to load $P_L = P_A$.

For $Z_G \neq Z_0$ it does not follow that matching the load will produce $P_L = P_A$ (see eq. 54). Maximizing power transfer more complicated.

Example 3-3.

Return loss: $L_R = 10 \log(P^+ / P^-)$ dB. Since $P^- = |\Gamma|^2 P^+$

$$L_R = \log \frac{1}{|\Gamma|^2} \text{ dB} \quad (56)$$

For lossless line L_R is the same anywhere (i.e. $|\Gamma|$ is independent of position).



Lossy line means position dependent L_R , but it is easily determined from $|\Gamma| = |\Gamma_L|e^{-2\alpha l}$. For input we have $\Gamma_{in} = |\Gamma_L|e^{-2\alpha l} \angle \phi_L - 2\beta l$ so that $L_{R,in} = L_{R,load} + 2(8.686\alpha l)$

Reflection loss: used only when $Z_G = Z_0$. Measures reduction in load power due to mismatch of load impedance ($Z_L \neq Z_0$)

$$\begin{aligned} \text{Ref. loss} &= 10 \log \frac{\overbrace{P_L(Z_L = Z_0)}^{=P_A e^{-2\alpha l}}}{\underbrace{P_L(Z_L)}_{=P_A e^{-2\alpha l}(1-|\Gamma_L|^2)}} \text{ dB} = 10 \log \frac{1}{1-|\Gamma_L|^2} \quad (57) \end{aligned}$$

aka mismatch loss.



1.6 Impedance transformation

Reference direction; impedance anywhere on line replaces everything to the right.

Starting point:

$$Z = Z_0 \frac{1 + \Gamma}{1 - \Gamma} = Z_0 \frac{1 + \Gamma_L e^{-2\gamma d}}{1 - \Gamma_L e^{-2\gamma d}} \quad (58)$$

After some manipulation (note: bar in, e.g. $\bar{Z} = Z/Z_0$ is for normalized values):

$$Z = Z_0 \frac{Z_L + Z_0 \tanh \gamma d}{Z_0 + Z_L \tanh \gamma d} \quad \bar{Z} = \frac{\bar{Z}_L + \tanh \gamma d}{1 + \bar{Z}_L \tanh \gamma d} \quad (59)$$



or for admittance

$$Y = Y_0 \frac{Y_L + Y_0 \tanh \gamma d}{Y_0 + Y_L \tanh \gamma d}, \quad \bar{Y} = \frac{\bar{Y}_L + \tanh \gamma d}{1 + \bar{Y}_L \tanh \gamma d} \quad (60)$$

Input impedance: set $d=l$; what about $d=0$?

If α is neglected

$$Z = Z_0 \frac{Z_L + jZ_0 \tan \beta d}{Z_0 + jZ_L \tan \beta d}, \quad \bar{Z} = \frac{\bar{Z}_L + j \tan \beta d}{1 + j\bar{Z}_L \tan \beta d} \quad (61)$$

and equivalent for Y-s

Example 3-4.



Dramatic changes in Z ; standing waves are the cause. No SW \Rightarrow no impedance transformation ($Z_L = Z_0 \Rightarrow Z = Z_0$ anywhere).

What happens at LF? $l \ll \lambda \Rightarrow \tan \beta l \approx 0$ so that $Z = Z_L$ for LF and low loss line.

Fixed length \Rightarrow freq. dependence of Z since $\beta l = \omega l/v = 2\pi l/\lambda$

Excellent for impedance transf. but bad for broadband design!

$\lambda/2$ line: $l = n\lambda/2$ then $Z_{in} = Z_L$ (substitute $\beta l = n\pi$ into eq. 59).

Impedance repeats itself every $\lambda/2$!!



Take $Z_G = Z_L$, both real (e.g. 20 Ohms). Tr. line has $Z_0 = 100$ Ohms and $l = \lambda/2$. $SWR = Z_0/R = 5$ but for this length of tr. line $Z_{in} = Z_L = 20$ Ohms. All available power is delivered down the lossless line to Z_L . Despite SW max. power is delivered to the load.

$\lambda/4$ line: $l = (2n - 1)\lambda/4$. Here $\tan \beta l \rightarrow \infty$ and $Z_{in} = Z_0^2/Z_L$ or normalized $\bar{Z}_{in} = 1/\bar{Z}_L$.

Large $Z_L \rightarrow$ small Z_{in} and inverse.

Inductive $Z_L \rightarrow$ capacitive Z_{in} (and inverse)

If Z_L behaves as a series resonant circuit Z_{in} is like parallel res. circuit.



For Z_L real it behaves like a transformer with turns ratio $n_t = \xi (= SWR)$ for $Z_L < Z_0$. But for $Z_L > Z_0, n_t < 1$.

Useful for matching a resistive load to generator (to deliver all available power). For Z_G real, Z_{in} must be real and $Z_{in} = R_G$ or $Z_0 = \sqrt{R_G R_L}$.

Since line is assumed lossless all power is delivered to the load.

Problem: works only at one (narrow range of) frequency.



Short circuit: obviously $Z_{in} = jX_{in} = jZ_0 \tan \beta l$. See fig. 3-14

For $\beta l < \pi/2$ (or $l < \lambda/4$) Z_{in} is inductive.

$$L_{eq} = X_{in}/\omega = Z_0 \tan(\beta l)/\omega \approx \underbrace{Z_0 l/v}_{\text{for } l < 0.08\lambda} = L'l \quad (62)$$

note that L_{eq} is freq. dependent. Think of this circuit as one turn of a coil (L).

Near $\beta l = n\pi/2$ and odd multiples S-C behaves like parallel resonant circuit.

Near $\beta l = n\pi$ S-C behaves like a series resonant circuit. see fig. 3-15.



Infinite number of resonances. Note on length: go for the shortest one ...

Open circuit: use admittances $Y_L = 0$ and $Y_{in} = jB_{in} = jY_0 \tan \beta l$
or $Z_{in} = -jZ_0 \cot \beta l$. Fig. 3-16;

For $l < \lambda/4$

$$C_{eq} = Y_0 \tan(\beta l) / \omega [F] \approx \underbrace{Y_0 l / v}_{l < 0.08\lambda} = l / (Z_0 v) = C' l \quad (63)$$

again it is freq. dependent; it looks like a parallel plate capacitor.

For $\beta l = \pi = 2\pi l / \lambda$ (i.e. $l = \lambda/2$) we have $Y_{in} = 0$ (O-C), but
for $l = (2n - 1)\lambda/4$, $Y_{in} = \infty$ (S-C).



- 1) near $\beta l = (2n - 1)\pi/2$ O-C behaves like series resonant circuit
- 2) near $\beta l = n\pi$ O-C looks like parallel resonant circuit.

