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**Seminar**  
**„Digitale Signalverarbeitung in Multimedia-Geräten“**

**SS 2003**

**Man-Machine-Interface (Video)**

Computation Engineering Student

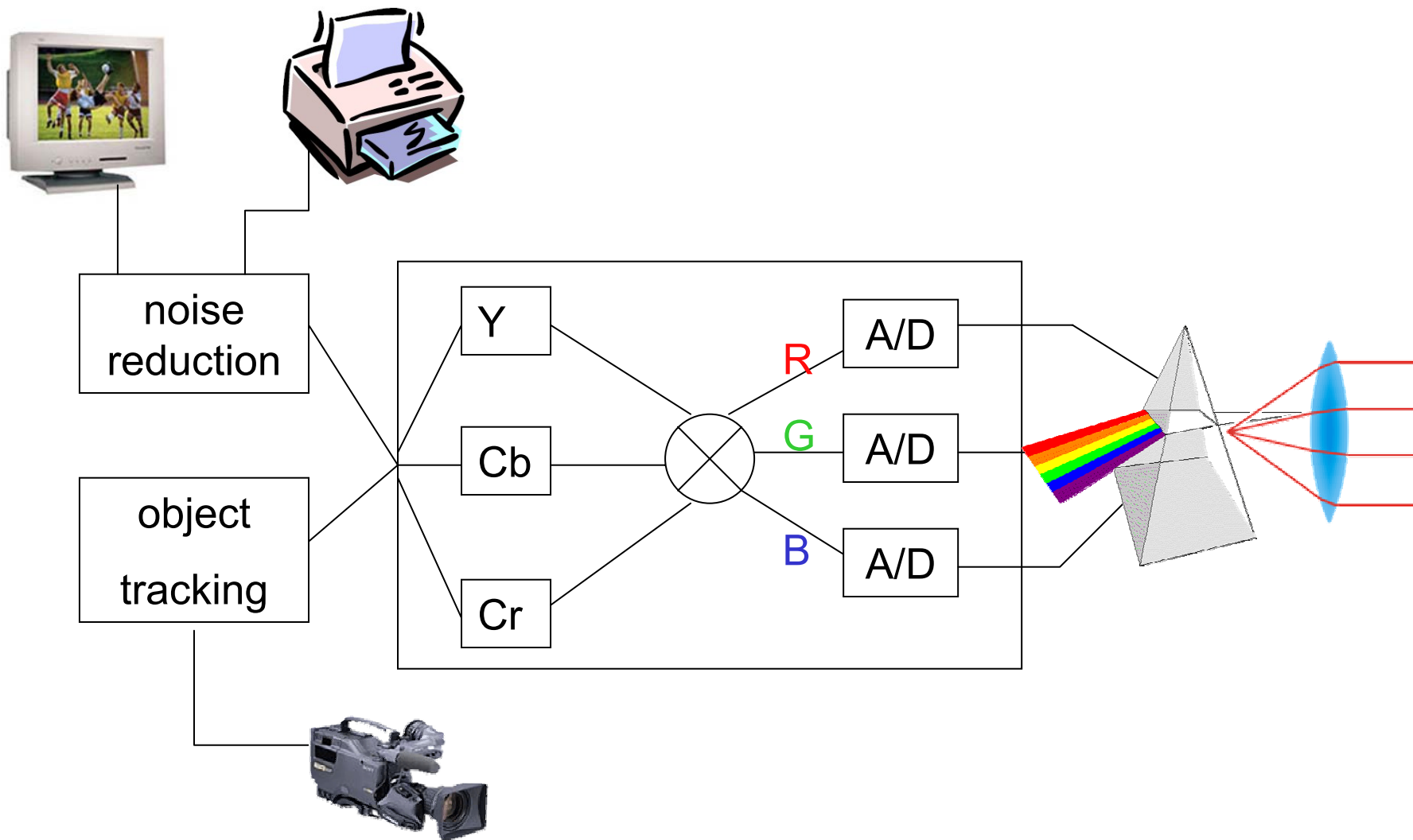
**Nataliya Nadtoka**

**coach: Jens Bialkowski**

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1. Processing Scheme
2. Human Visual System
3. Video Representation
  1. Progressive and Interlaced scan
  2. Chrominance subsampling
  3. Color Spaces
4. Object Detection – Face Detection Overview
5. Demonstration

# Processing scheme



# Human Visual System - Color Perception and representation

## Cones

color

low sensitivity

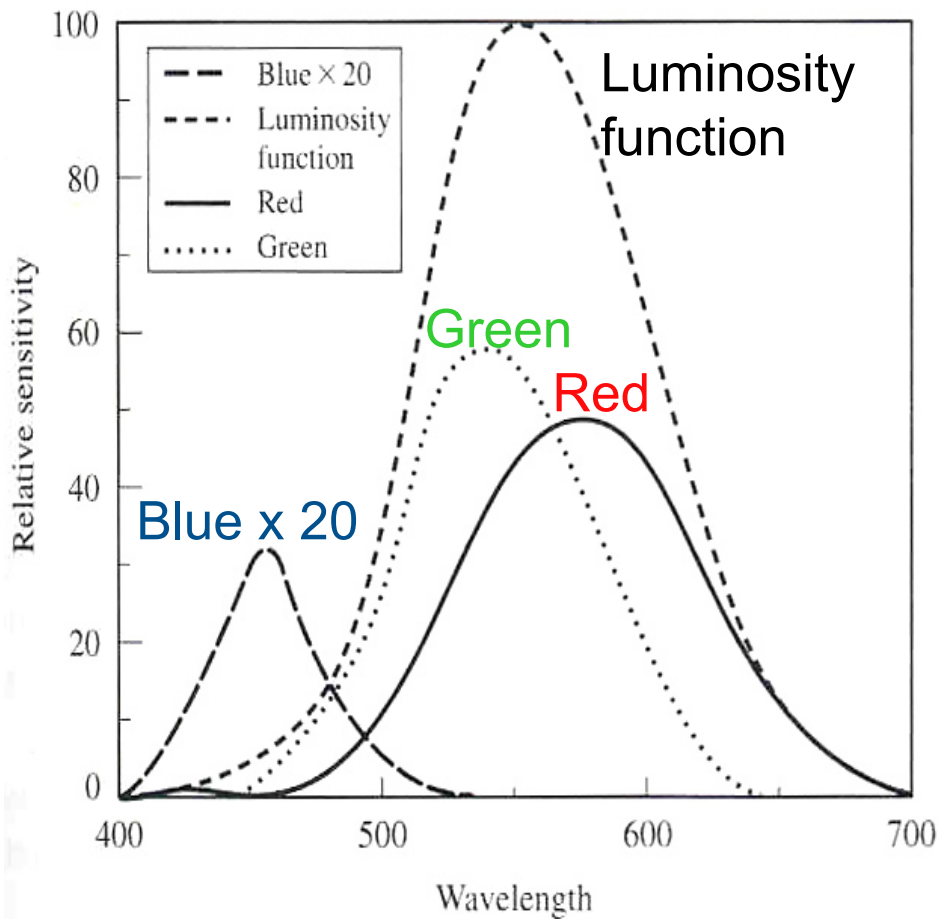
6 Million

## Rods

monochrome

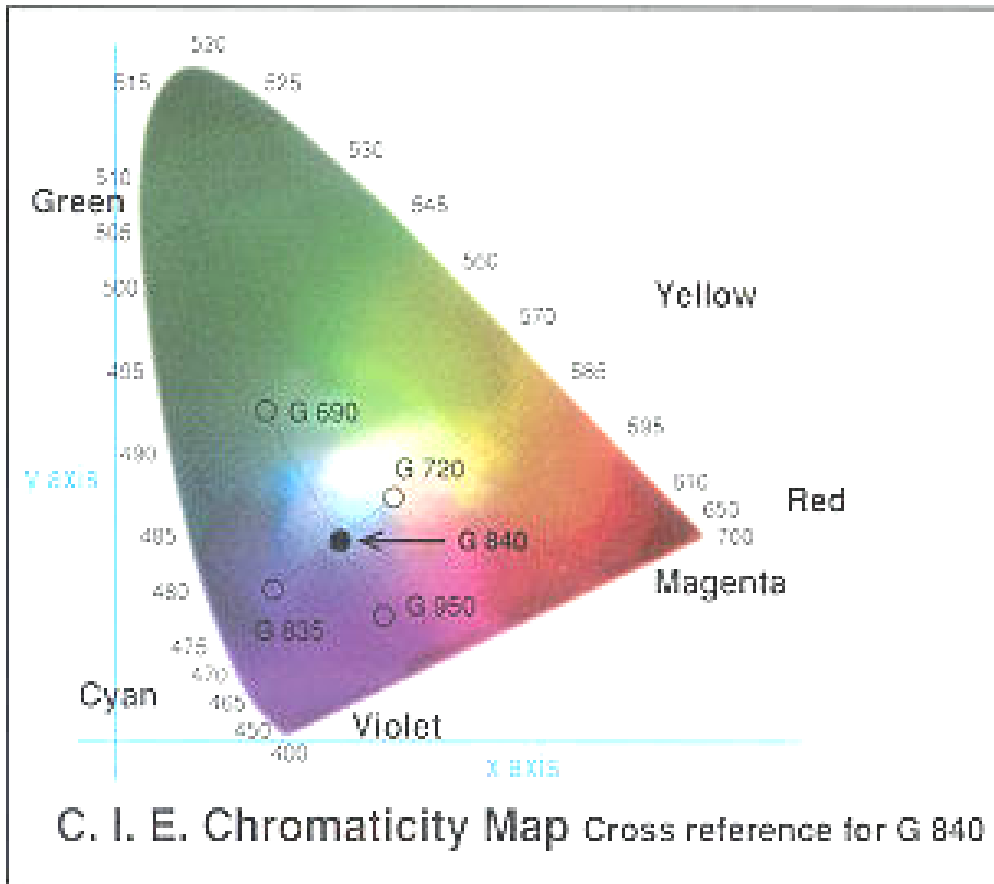
high sensitivity

120 Million



Frequency responses of 3 types of cones in human retina and luminous efficiency function

# HVS - Color Gamut



Tristimulus values:

X, Y, Z – intensities of **Red**,  
**Green** and **Blue**

Chromaticity coordinates:

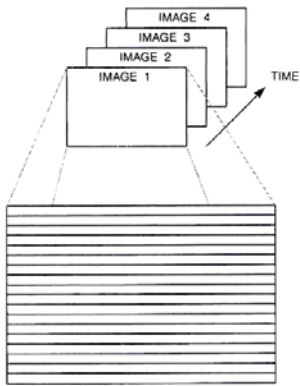
$$x = \frac{X}{X+Y+Z} = \frac{\text{red}}{\text{red} + \text{green} + \text{blue}}$$

$$y = \frac{Y}{X+Y+Z} = \frac{\text{green}}{\text{red} + \text{green} + \text{blue}}$$

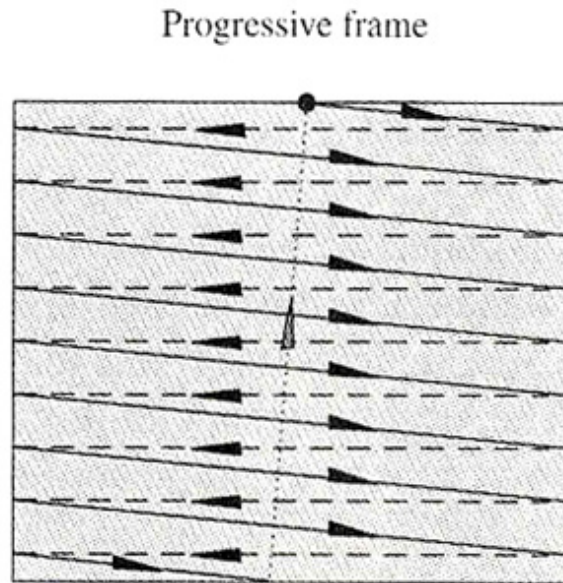
$$z = \frac{Z}{X+Y+Z} = \frac{\text{blue}}{\text{red} + \text{green} + \text{blue}}$$

$$x + y + z = 1$$

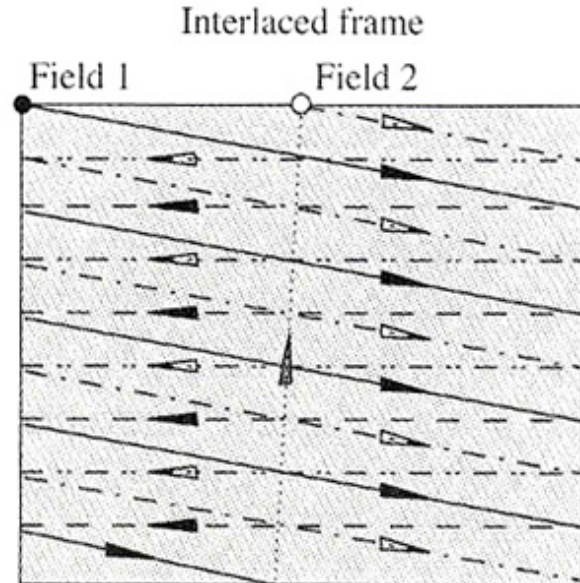
# Raster Scan - Progressive and Interlaced Scan



In a raster scan a camera captures a video sequence by sampling it in both temporal and vertical directions.



(a)



(b)

Electronic or optic beam of an analog video camera continuously scans the imaged region from the top to bottom and then back to the top

# Progressive and Interlaced scan (continued)

**Progressive scan:** horizontal lines are scanned successively

**Interlaced scan:** each frame is scanned in 2 fields

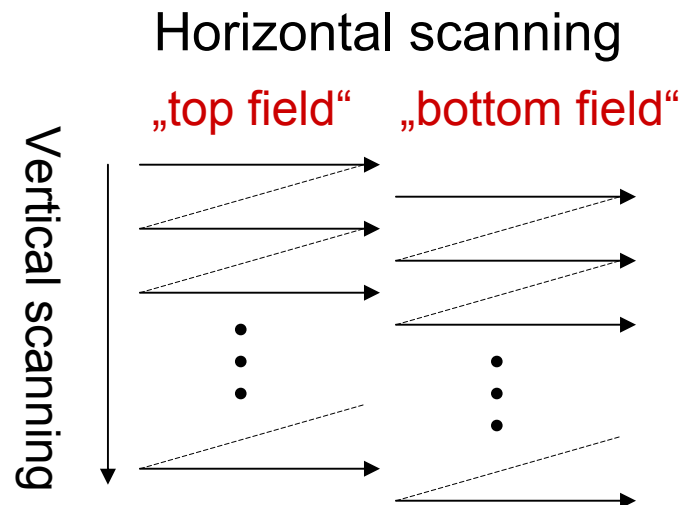
**Motivation:** trade-off the vertical resolution for an enhanced temporal resolution given the total number of lines that can be recorded within time

## Interlaced

- each scan line is refreshed half as often
- limited line-to-line changes

## Progressive

- no limit on the line-to-line changes
- high resolution image (vertically)





# „Z- effect“ illustration



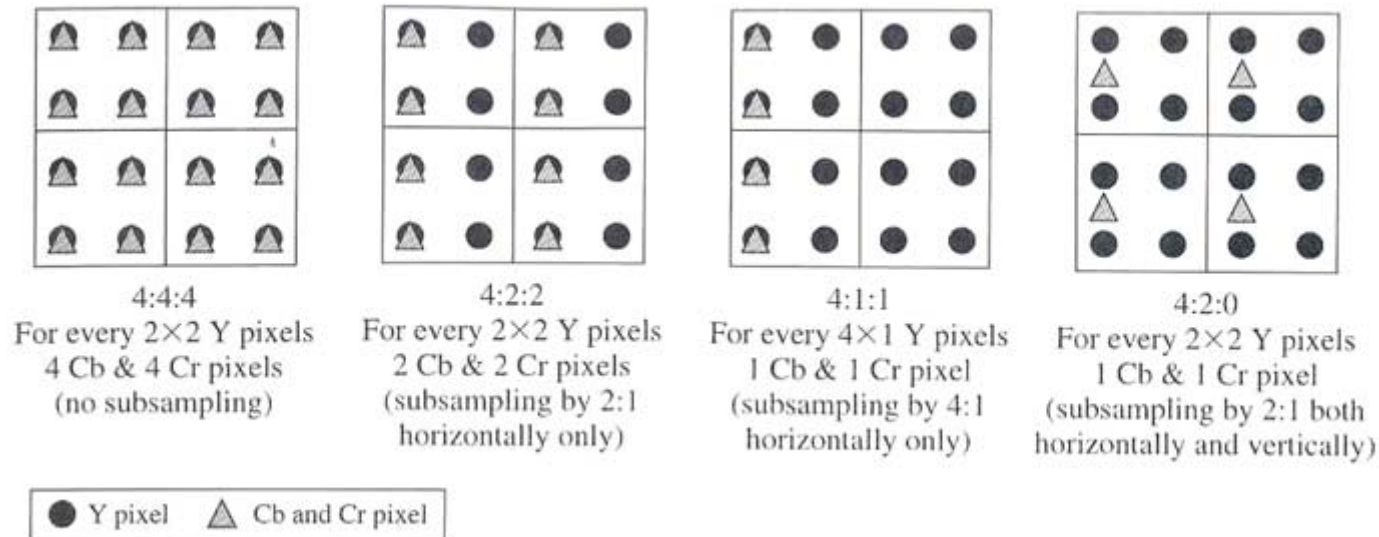


# „Z- effect“ illustration (continued)

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# Color Coordinates and Chrominance Subsampling



BT.601 chrominance subsampling formats.

**Reason:** human vision has a higher resolution for luminance than for chrominance components

# Color Spaces

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A **Color Space** is a mathematical representation of a set of colors.

The most popular color models:

RGB	computer graphics, cameras, scanners
YUV	PAL, NTSC, SECAM (Europe) television
YCbCr	compression in video systems (JPEG, MPEG 1-4)
HSV	„artists work“ postprocessing
CMYK	printers

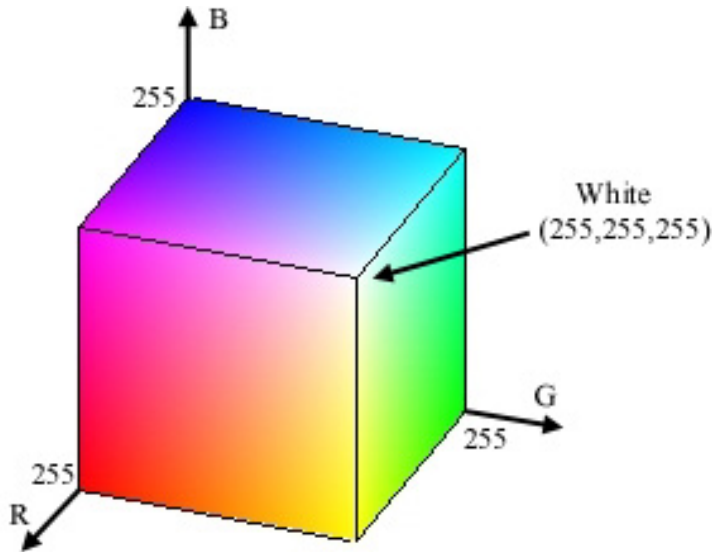
# RGB Color Space

Red, Green and Blue are *primary additive colors*

- used as phosphors by CRTs
- basic colors for computer graphics, digital cameras

## Drawbacks:

- equal bandwidth requirements
- high computational effort
- luminance and chrominance



RGB cube

# YUV Color Space

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- Used in NTSC, PAL TV standards (Europe):
  - black & white systems are supported by Y luminance component
  - color (U and V) was added to display color picture
- conversion works on gamma corrected RGB signal ( $R'$   $G'$   $B'$ ):

$$Y = 0.299 R' + 0.587 G' + 0.114 B'$$

$$U = -0.147 R' - 0.289 G' + 0.436 B' = 0.492 (B' - Y)$$

$$V = 0.615 R' - 0.515 G' - 0.100 B' = 0.877 (R' - Y)$$

# YCbCr Color Space

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- part of ITU-R BT.601 world wide digital component video standard
- scaled and offset version of YUV(luminance and chrominance are scaled additionally)
- Y [16..235], Cb and Cr [16..240]
- comes in different subsampling formats (4:4:4, 4:2:2, 4:2:0)
- used in compression MPEG 1-4, JPEG

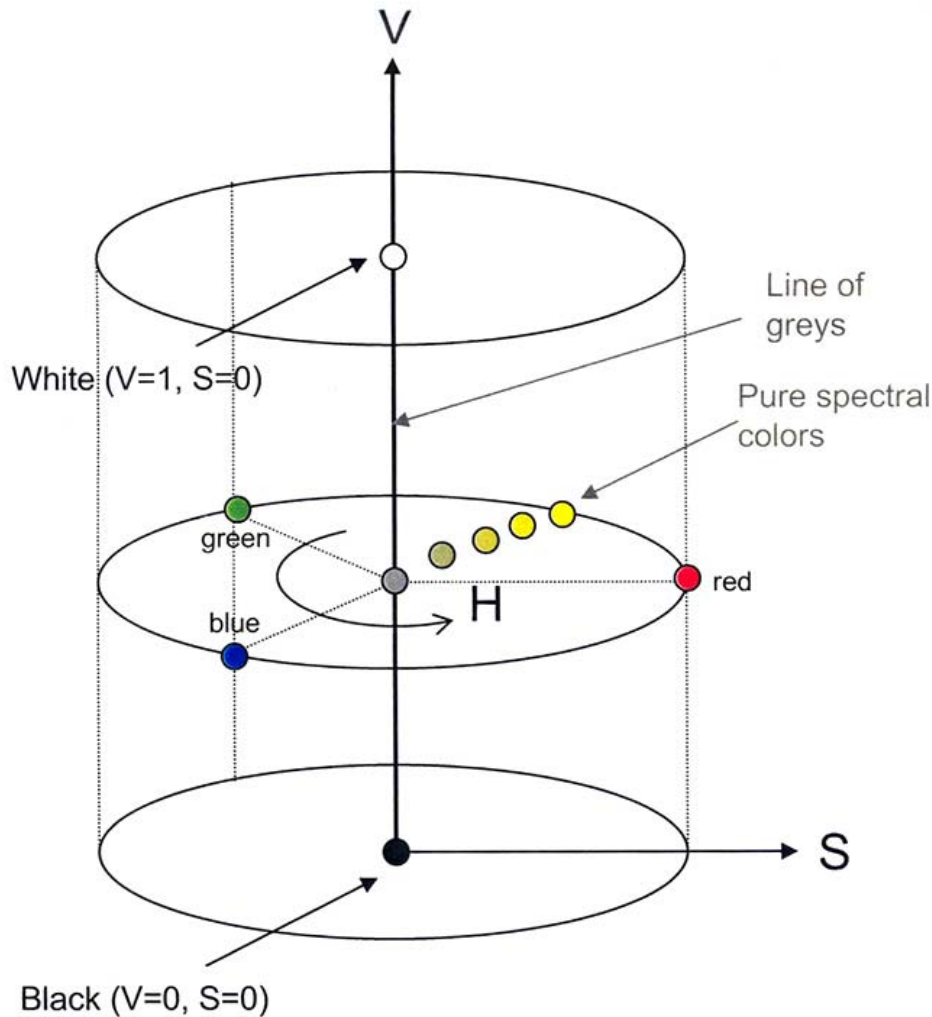
$$Y_{601} = 0.299 R' + 0.587 G' + 0.114 B'$$

$$C_b = -0.172 R' - 0.339 G' + 0.511 B' + 128$$

$$C_r = 0.511 R' - 0.428 G' - 0.083 B' + 128$$



# HSV Color Space



H( Hue)

S( Saturation)

V( Value of intensity)  
„brightness“

**non-linear transform** from RGB  
tristimulus to color cylinder

HSV color system defined by  
C.I.E.(International Commission  
for Illumination)

# Object detection – Face Detection

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**Goal:** make man – machine interface more humane

Research in face processing includes:

- Face Recognition
- Face Tracking
- Pose Estimation
- Expression Recognition
- Gesture Recognition

# Face detection

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- ⇒ **Given:** a single image or sequence of images
- ⇒ **Goal:** identify all image regions containing face regardless its three dimensional position and orientation and the lighting conditions
- ⇒ **Challenges:**
  - **Pose** (frontal, 45 degree, profile, upside down)
  - **Presence or absence of structural components** (beards, mustaches, glasses)
  - **Facial expression**
  - **Occlusion**
  - **Image orientation**
  - **Imaging Conditions** (lighting, camera characteristics)

# Face detection approach

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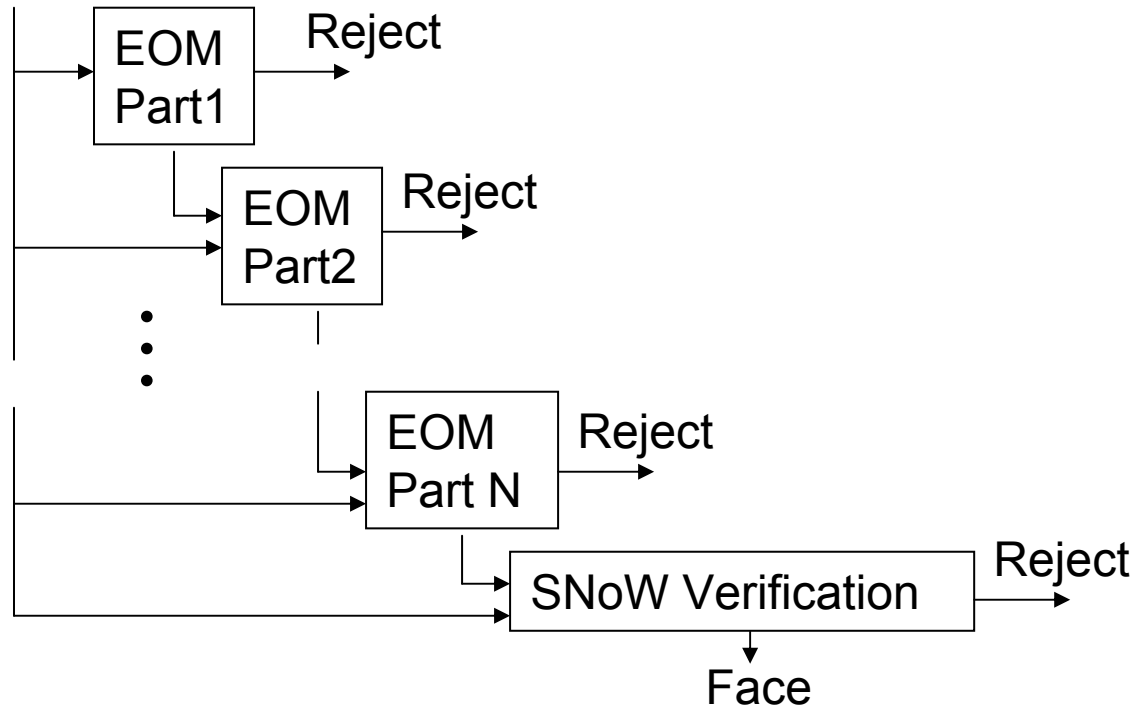
- ⇒ Knowledge based - multilevel rule-based method with mosaicing
- ⇒ Feature invariant
  - Facial features                      grouping of edges
  - Texture                                Space Gray-Level Dependence Matrix of face
  - Skin Color                            Mixture of Gaussian
  - Multiple features                    Integration of skin color, size and shape
- ⇒ Template matching                      Human defined face templates
- ⇒ Appearance based method
  - Eigenface                            Eigenvector decomposition and clustering
  - Distribution based                    Gaussian distribution and multilayer perception
  - Neural Network                      Ensemble of neural networks and arbitration
  - Support Vector Machine            Training SVM with RBF kernel
  - Bayesian approach                   Naive Bayes Classifier on local appearance
  - Hidden Markow Model               Higher order statistics with HMM
  - Information-Theoretical Approach   Kullback relative information

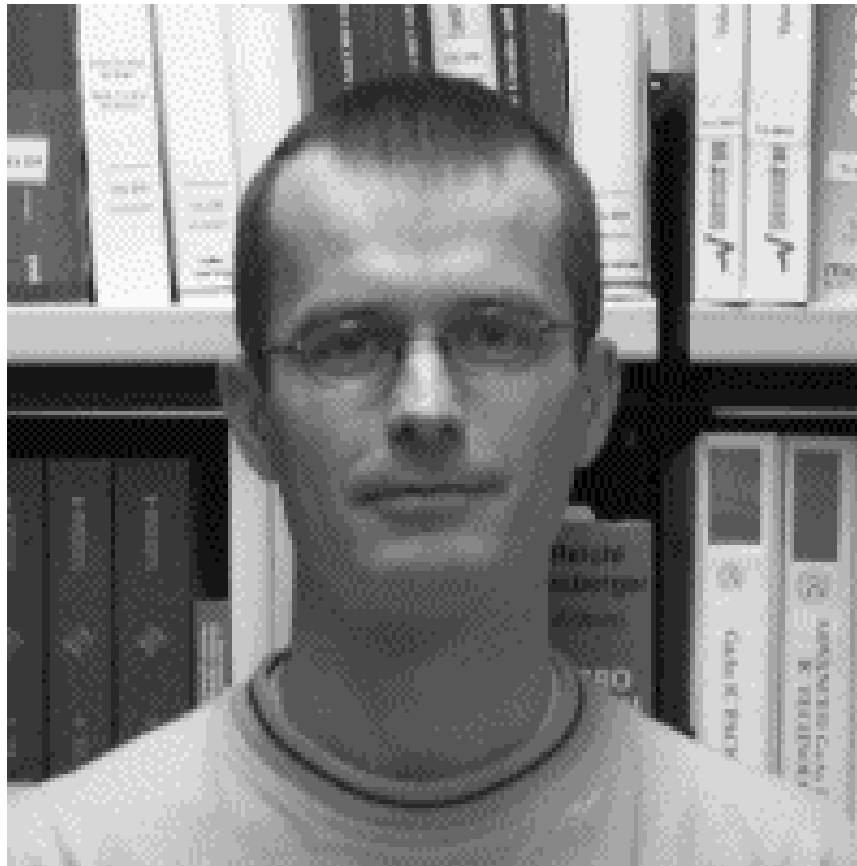
# Face Detection at Video Frame Rate Based on Edge Orientation Features (B. Fröba and C. Küblbeck, Fraunhofer Gesellschaft)

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- ⇒ **Works** with still images and video streams
- ⇒ Uses a combination of two approaches
  - Edge Orientation Matching
  - Appearance based method (called SNoW)

Analysis Window







# Conclusions

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- ⇒ Video recording is physical representation (voltage)
- ⇒ Further digital processing with respect to Human Visual System, e.g.:
  - For trading the amount of data, e.g.
    - Progressive vs. Interlaced Scan
    - Color Subsampling
  - For representing Color and Brightness:
    - RGB
    - YUV
    - YCbCr
    - HSV
  - Object detection
  - And more: e.g. quality improvement (e.g. Denoising, Edge Enhancement, ...)
- ⇒ Man-Machine-Interface brings together video recording and human visual system

# Reference

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- ⇒ Neith Jack: " Video Demystified" 3<sup>rd</sup> Ed.
- ⇒ Wang, Ostermann, Zhang: "Video Processing and Communications", Prentice Hall, 2001
- ⇒ Kaup, Script Multimedia Communications, Uni Erlangen-Nürnberg
- ⇒ Ming-Hsuan Yang, David Kriegman, Narendra Ahuja "Detecting Faces in Images: A Survey", University of Illinois
- ⇒ Bernhard Fröba, Christian Küblbeck, "Robust Face Detection at Video Frame Based on Edge Orientation Features", Fraunhofer Institute for Integrated Circuits
- ⇒ [www.iis.fraunhofer.de/bv/](http://www.iis.fraunhofer.de/bv/)